

ON EFFICIENCY OF MODELING AN EQUIPROBABLY DISTRIBUTED SYSTEM OF RANDOM VARIABLES

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Abstract. We suggest a modified algorithm of modeling an equiprobably distributed system of discrete random variables based on a non-equiprobably distributed system of discrete random variables with the same set of possible values. The efficiency of modeling is estimated.

Keywords: equiprobable generation; algorithm efficiency.

In [1, 2] a method is suggested which solves the problem of equiprobable generation of values for a system of discrete random variables. The solution is based on a non-equiprobable generator of another system of discrete random variables with the same set of possible values.

Namely, let $X = (X_1, \dots, X_n)$ be a system of n discrete random variables with a finite set of possible values $x^i = (x_1^i, \dots, x_n^i), i = 1, \dots, N$. Let the probability distribution of the system be $P(X = x^i) = p_i, i = 1, \dots, N, \sum_{i=1}^N p_i = 1$.

Assume

$p = \min_{i=1, \dots, N} p_i, p_i = p + \Delta_i, \Delta_i \geq 0, i = 1, \dots, N$. Then, given the normalization

$$\sum_{i=1}^N p_i = 1$$

we have

$$\sum_{i=1}^N \Delta_i = 1 - Np.$$

Consider a new system of discrete random variables $Z = (Z_1, \dots, Z_n)$, whose values are generated by the algorithm $EQPR(Z)$.

Algorithm $EQPR(Z)$

1. Generate values for the system of random variables X according to its probability distribution. Let $X = x^i$ be the result of the step.

2. Generate values for an auxiliary system of random variables Y_i according to its probability

distribution $P(Y_i = 0) = \frac{\Delta_i}{p_i}, P(Y_i = 1) = \frac{p}{p_i}$.

3. If $Y_i = 1$, then set $Z = x^i$; else go to step 1 of the algorithm.

The system Z is proved to be equiprobably distributed, i.e.

$$P(Z = x^i) = \frac{1}{N}, i = 1, \dots, N.$$

The chosen measure of efficiency of $EQPR(Z)$ is the expectation $M[V]$ of the random variable V , which is the number of iterations required to deliver a realization of Z . It is proven that

$$M[V] = \frac{1}{Np}. \quad (1)$$

From (1) it follows that if p is rather small then delivering a realization of Z requires a lot of iterations. In this case the method efficiency is low. Therefore, increasing the efficiency of the suggested method of equiprobable generation is relevant.

In this paper we modify the described generator for an equiprobably distributed system of discrete random variables. We also show the modified algorithm can be substantially more efficient than the original $EQPR(Z)$.

PROBLEM STATEMENT AND SOLUTION

Let $X = (X_1, \dots, X_n)$ be the system of discrete random variables defined above. Let A be a finite set of possible values of $X, |A| = N$. Let a set of equinumerous sets $A_k, |A_k| = L = N/K, k = 1, \dots, K$ be a partition of A . Let $p_j^k, k = 1, \dots, K, j = 1, \dots, L$ be a probability of the j -th element of A_k . Assume

$$p^k = \min_{j=1, \dots, L} p_j^k. \quad (2)$$

Let $W^k = (W_1^k, \dots, W_n^k)$ be a system of discrete random variables with the set A_k of possible values and their corresponding probabilities

$$\frac{p_j^k}{\sum_{j=1}^L p_j^k}, k = 1, \dots, K.$$

Consider a new system of discrete random variables $U = (U_1, \dots, U_n)$ whose values are generated by the algorithm $EQPRM(U)$.

Algorithm $EQPRM(U)$

Generate equiprobably a number k of a subset of A .

Generate a realization w^k of the system W^k applying $EQPR(W^k)$ to the system W^k ; note that the realization w^k coincides with a possible value x^i of the system X , $w^k = x^i$.

Assume $U = w^k = x^i$.

Obviously, the set of possible values of U is the set A .

Proposition 1

The system of random variables U is distributed equiprobably:

$$P(U = x^i) = \frac{1}{N}, i = 1, \dots, N.$$

Proof. Let $x^i \in A^k$ and let α^k be an event of selecting number k on Step 1 of the algorithm $EQPRM(U)$ or, equally, selecting a subset A^k to be processed on the next step. Then

$$P(U = x^i) = P(U = x^i / \alpha^k) \cdot P(\alpha^k).$$

According to $EQPRM(U)$ we have

- $P(\alpha^k) = \frac{1}{K}$ by Step 1 of $EQPRM(U)$;
- $P(U = x^i / \alpha^k) = \frac{1}{L}$ by Step 2 of

$EQPRM(U)$ taking into account W^k and the result of $EQPR(W^k)$.

Therefore

$$P(U = x^i) = \frac{1}{L} \cdot \frac{1}{K} = \frac{1}{LK} = \frac{1}{N},$$

since $L = \frac{N}{K}$.

The proposition is proved.

Assume V_M is the number of iterations required to obtain a realization of the system U . Specifically, V_M is the sum of the only iteration of Step 1 and all the iterations of $EQPR(W^k)$ on Step 2. Let the expectation $M[V_M]$ be a measure of efficiency of $EQPRM(U)$.

According to (1), the expectation of the number of iterations of $EQPR(W^k)$ is

$$\frac{1}{L \cdot \frac{p^k}{\sum_{j=1}^L p_j^k}}.$$

Since it is the conditional expectation of the number of iterations on Step 2 of $EQPRM(U)$ under the condition of equiprobable selection of A^k on Step 1, we obtain

$$M[V_M] = 1 + \sum_{k=1}^K \frac{1}{L \cdot \frac{p^k}{\sum_{j=1}^L p_j^k}} \cdot \frac{1}{K} =$$

$$= 1 + \frac{1}{KL} \sum_{k=1}^K \frac{\sum_{j=1}^L p_j^k}{p^k} = 1 + \frac{1}{N} \sum_{k=1}^K \frac{\sum_{j=1}^L p_j^k}{p^k}.$$

Therefore, the required measure of efficiency is

$$M[V_M] = 1 + \frac{1}{N} \sum_{k=1}^K \left(\frac{1}{p^k} \sum_{j=1}^L p_j^k \right). \quad (3)$$

Regarding the upper and the lower bounds of $M[V_M]$ we claim that:

Proposition 2

$$2 \leq M[V_M] \leq 1 + \frac{1}{Np}. \quad (4)$$

Proof. Obviously,

$$M[V_M] \geq 2, \quad (5)$$

since we always have at least Step1 of $EQPRM(U)$ and at least one iteration on Step 2. The lower bound (5) is attainable since as $p_j^k = p^k, k = 1, \dots, K, j = 1, \dots, L$ we have

$$M[V_M] = 1 + \frac{1}{N} \sum_{k=1}^K \frac{1}{p^k} \sum_{j=1}^L p_j^k = 1 + \frac{K \cdot L}{N} = 1 + \frac{N}{N} = 2.$$

Taking into account that $\frac{1}{p^k} \leq \frac{1}{p}, k = 1, \dots, K$, we

can obtain the upper bound of $M[V_M]$ as follows.

$$M[V_M] = 1 + \frac{1}{N} \sum_{k=1}^K \left(\frac{1}{p^k} \sum_{j=1}^L p_j^k \right) \leq 1 + \frac{1}{N} \cdot \frac{1}{p} \sum_{k=1}^K \sum_{j=1}^L p_j^k =$$

$$= 1 + \frac{1}{Np} \sum_{i=1}^N p_i = 1 + \frac{1}{Np},$$

i. e.

$$M[V_M] \leq 1 + \frac{1}{Np}. \quad (6)$$

Obviously, the upper bound (6) is attainable as $p^k = p, k = 1, \dots, K$.

Combining (5) and (6), we get (4).

Now compare $M[V]$ and $M[V_M]$, which are the measures of efficiency of $EQPR(V)$ and $EQPRM(U)$, respectively, for the same system X of random variables. The minimum of $M[V]$ is 1, which is attainable, according to (1), as $p = \frac{1}{N}$. It follows that, obviously, since Step 1 of $EQPRM(U)$ is always executed, then $M[V] < M[V_M]$ under “the best” and “the worst” conditions. However, from (1) and (3) we obtain the condition of $EQPRM(U)$ being preferable to $EQPR(V)$ according to the defined measure of efficiency: $M[V_M] < M[V]$ if

$$\sum_{k=1}^K \left(\frac{1}{p^k} \sum_{j=1}^L p_j^k \right) < \frac{1-Np}{p}. \quad (7)$$

Example

Assume $N = 1000$, $K = 2$, $p = p^1 = 0.0001$, $p^2 = 0.001$, $\sum_{j=1}^{500} p_j^1 = 0.1$, $\sum_{j=1}^{500} p_j^2 = 0.9$.

Then, from (3) we get $M[V_M] = 2.9$, from (1) we get $M[V] = 10$, i.e. here $EQPRM$ is 3.5 times more efficient than $EQPR$.

CONCLUSION

The suggested algorithm $EQPRM$ can be substantially more efficient in practice than its predecessor $EQPR$. It follows from the proof of the Proposition 2 that, when partitioning a set A to blocks containing nearly equiprobable elements, we get the efficiency of $EQPRM$ close to its lower bound, which equals 2.

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МЕТАДААННЫЕ

Название: Об эффективности моделирования равновероятно распределенной системы случайных величин

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Аннотация: Предложен модифицированный алгоритм моделирования равновероятно распределенной системы дискретных случайных величин, основанный на неравновероятно распределенной системе дискретных случайных величин с таким же набором возможных значений. Оценена эффективность моделирования.

Ключевые слова: равновероятная генерация; эффективность алгоритма.

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